

The BUB-Tree

(bounding UB-Tree)

dealing with dead space

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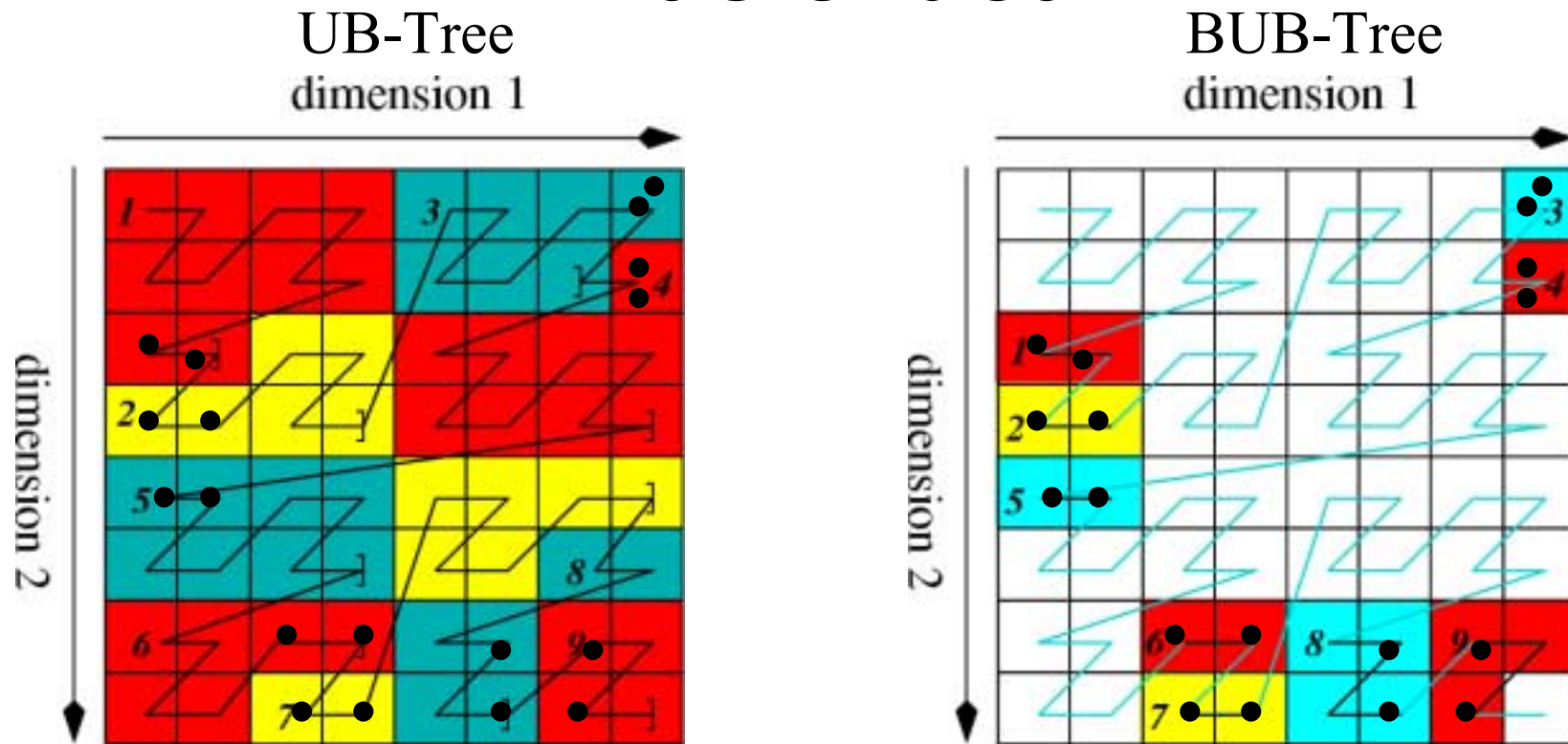
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Motivation

Objective: Multidimensional indexing

- real data is always skewed
 - data warehousing
 - spatial data
- ⇒ there is a lot of dead space
- UB-Tree partitions the whole universe
- ⇒ good performance in general, but queries on dead space suffer
- has the R-Tree a “better” partitioning?

Basic Idea



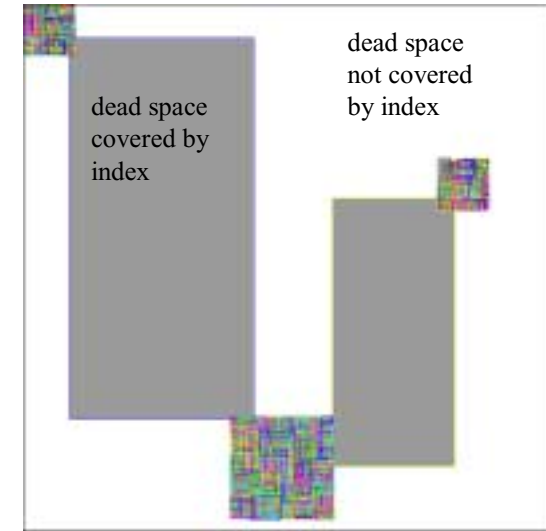
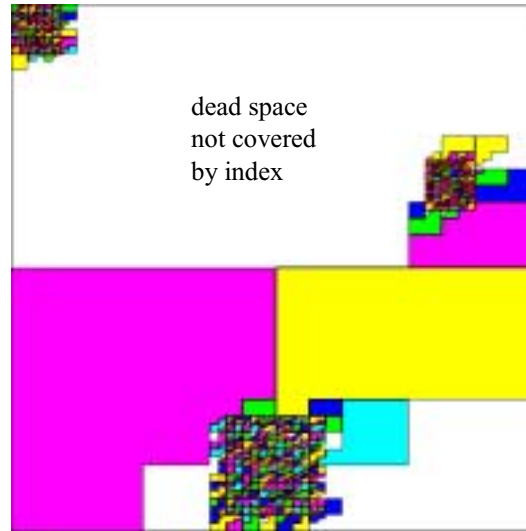
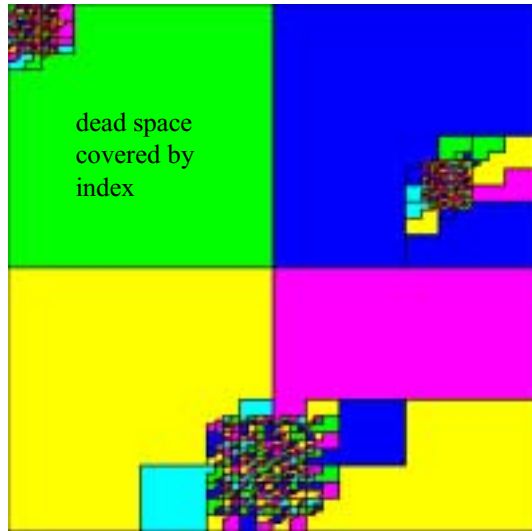
- use Z-intervals instead of Z-separators
 - store (zstart, zend) in a B-Tree
- ⇒ higher index levels reflect Z-intervals of lower ones

UB-Tree

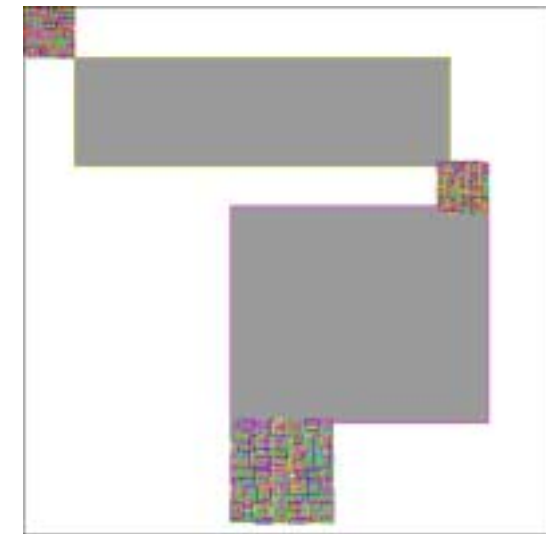
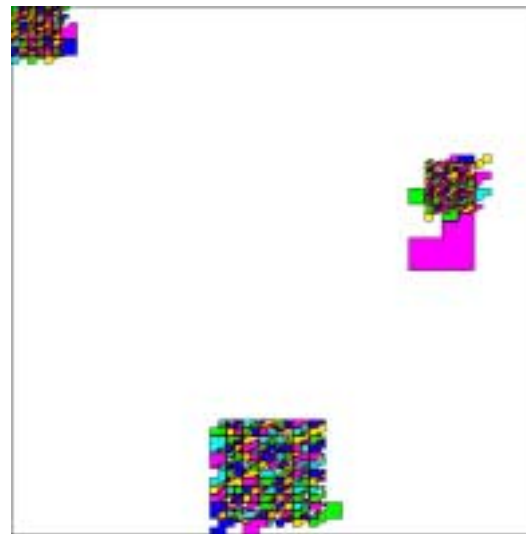
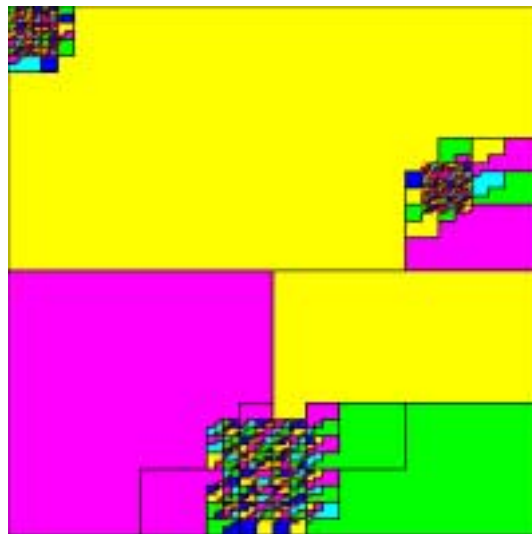
BUB-Tree

R*-Tree

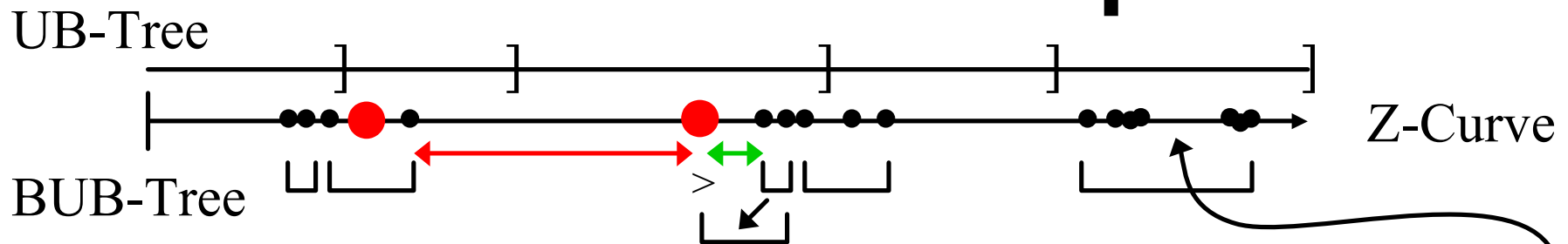
Random Insert



Bulk Load

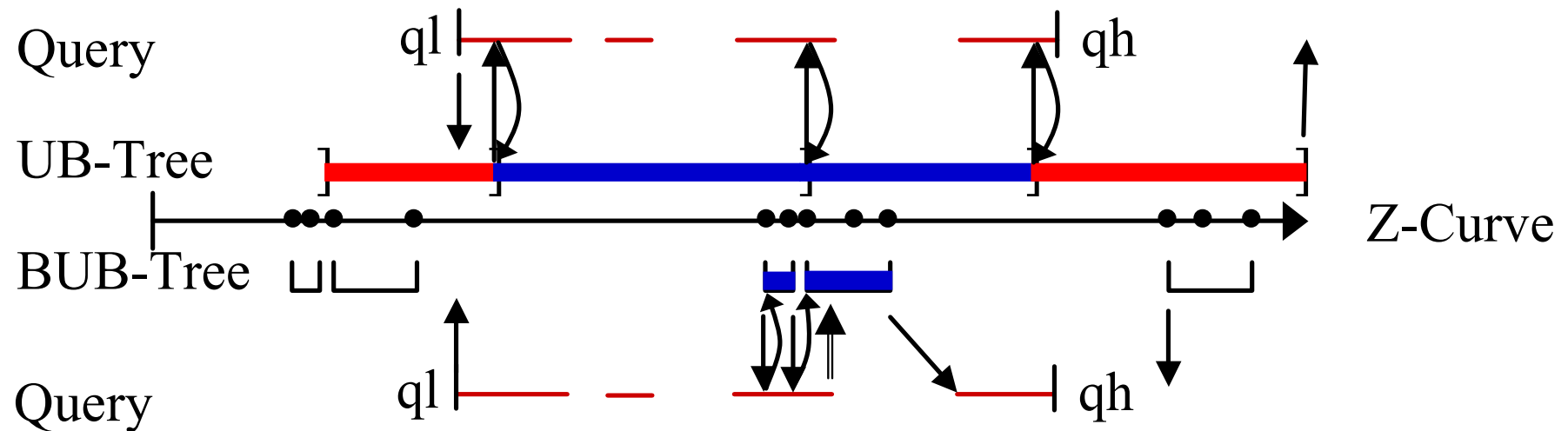


Insertion and Split



- find nearest Z-Region w.r.to Z-order and insert there
cost: *height* page reads, 1 page write, binary search on pages
- fix region boundaries if inserting at start/end
worst case cost: *height* page reads & writes
- split between tuples with biggest Z-distance
the goal: minimize the space covered by the index!!!
 - honor minimum fill rate
 - split only when Z-gap volume exceeds a given % of Z-region volume
 - split only when Z-gap volume exceeds a given volume

Range Query



- we need two algorithms developed for UB-Trees
 - NextJumpIn(z): calculates next intersection point greater than z of the Z-curve with the query box
 - NextJumpOut(z): calculates the point greater than z (where Z is within the query box) on the Z-curve where it leaves the query box again

Summary

- “twice” the space requirements for index part
 - reduced index fanout,
 - + but high potential for compression due to prefixes
- + „only“ populated parts of the universe are indexed
- + UB-Tree basic algorithms can be reused
- + still a disjoint space partitioning
- + logarithmic cost for basic operations, i.e. it is a dynamic index structure which is not true for the R*-Tree!
- + query performance equal or better to R*-Tree
 - + also with dual space approach for GIS data