# Translating Aggregate Queries into Iterative Programs 

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#### Abstract

Over the last decade, many techniques for optimizing relational queries have been developed. However, the optimization of queries with aggregation has received little attention.

This paper investigates possible improvements for aggregate queries on groups of tuples. We suggest the use of program transformation methods to systematically generate efficient iterative programs for their evaluation. Two transformation steps successively translate a program, which sorts the relation before applying the aggregate function, into an iterative program which performs the aggregation while sorting, thus using less time and space than needed for the execution of the initial program.


## 1. Introduction

Many database management systems (DBMSs), such as SYSTEM $R$ and INGRES, permit the computation of counts, sums, averages and other aggregate quantities [ASTR76, STONE76]. Aggregation is usually performed over a set of tuples yiclding a singleton valuc. We can also partition, or group, tuples of a relation into subsets according to common values of one or more attributes. The aggregation is then performed over each of the subsets yielding a set of singleton values. For example, consider the SQL query:

## SELECT SUM(Salary) FROM EMP <br> GROUP BY Department

on Relation EMP (EMP\#, Salary, Department). This query computes the sum of salaries for each department in the EMP relation. As the number of departments is not known in advance, one possible evaluation strategy is to sort the relation EMP on department values before the salary sum for each department is computed by scanning the sorted relation once.

This processing strategy is not optimal. Klug notices that in many cases the aggregate computation - or at least part of it - may be performed while sorting [KLUG82]. For instance, in the above example, whenever two tuples are compared during the sort and they agree in their department values, we can merge them into a
new tuple by adding their salaries. The sort then continues with the newly generated tuple. Applying this change throughout the sort, the final result is a relation, sorted on the department values, with exactly one tuple for each department recording its salary. An additional scan of the relation to perform aggregation becomes unnecessary. An additional gain in execution speed results from a decreasing number of tuples during the sort, thus requiring less time for sorting and less storage space. Klug suggests a specially designed sort function which implements the combination of sorting and aggregation [KLUG82].

In this paper we derive the suggested improvements for aggregate functions by methods of program transformation [BACK78, DARL76, BURS77]. We generate the efficient programs, as described above, from initial specifications which independently define the aggregate function and the sort algorithm.

The transformation consists of two phases. The first phase, which we call the horizontal transformation phase, transforms the initial program specifications for sorting and aggregation into the desired optimal program form. Horizontal transformation manipulates highlevel program specifications which are based on Backus' FP language [BACK78]. To guarantee fast execution, the second phase, which we call the vertical transformation phase, translates the high level specification into an iterative program in a PASCAL-like notation.

To make the discussion of the transformation more concrete, we choose one sort algorithm and one aggregate function. To implement sorting we use the sort-merge algorithm [KNUT73]. We demonstrate all transformation steps using the aggregate function sum_by which performs the summation of values on groups of tuples. Later we show how the proposed transformation generalizes to other aggregate functions as well.

The paper is organized as follows. In the next section we provide some more motivation for using methods of program transformation to generate efficient programs for the evaluation of aggregate functions. In Section 3 we introduce the notation for describing the sort and the aggregate function before Section 4 develops the transformation steps to generate the improved program. In Section 5 we generalize the transformation of Section 4 to other aggregate functions by introducing a uniform definition which is better suited for formal manipulation.

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## 2. Motivation

Query languages for relational DBMSs, such as QUEL [STONE76] or SQL [ASTR76], permit the user to express database requests in a clear and understandable form that describes properties of the requested result without considering aspects of an efficient execution. Therefore it is the DBMS's responsibility to derive an evaluation strategy to compute the query efficiently. The component of the DBMS which decides on the strategy is called the query optimizer. Based on the information about the internal representation of the data accessed and the available evaluation strategies, the query optimizer produces a query evaluation plan (QEP). For example, the existence of indices or information about the physical order of elements in the relation influences the optimizer's choice of either an index-join, a merge-join, or a nested-loop join as the optimal evaluation strategy for a join operator. Jarke and Koch give a comprehensive overview on various optimization techniques for relational queries [JARK84].

After its generation by the query optimizer, the QEP has to be executed against the database to compute the requested result. To perform this task, many DBMSs face a translation problem since the QEP most often uses operations on sets of tuples, while the execution system performs operations on tuples to ensure an efficient execution [ASTR76, STONE76]. This gap between the generated QEP and the query execution system introduces the problem of mapping QEPs into sequences of operations for the execution system. We call this problem the query translation problem [FREY85a, FREY85b].

In many ways, both translation steps, i.e. optimization and query translation into operations for a specific exccution system, resemble a specialized program transformation problem. Generally speaking, program transformation promises to provide a comprehensive solution to the problem of producing programs which try to solve several incompatible goals simultaneously: On the one hand, programs should be correct and clearly structured, thus allowing easy modification. On the other hand, one expects them to be executed efficiently. Using languages like C or PASCAL for implementation of programs, one is immediately forced to consider aspects of efficiency that are often unrelated to their correctness, natural structure, and clarity.

For this reason, the transformational approach tries to separate these two concerns by dividing the programming task into two steps: The first step concentrates on producing programs that are written as clearly and understandably as possible without considering efficiency issues. If initially the question of efficiency is completely ignored, the resulting program might be written very comprehensibly, but might be highly inefficient or even unexecutable. The second step then successively transforms programs into more efficient ones - possibly based on additional information - using methods which preserve the meaning of the original program.

In our opinion, these intentions exactly guided the design of query languages for relational DBMSs where queries are expressed in a data independent manner. We therefore argue that methods which have been developed in the area of program transformation may prove useful for the translation of relational queries. In [FREY85b] we describe the transformation of aigebra-based query specifications into iterative programs which are executable on a tuple-oriented query execution system. The transformation inyolves the rule-based manipulation of recursively defined programs and the replacement of recursion by iteration both of which were the focus of early research in program transformation [DARL76, BURSS77, COHE80].

In 1978 John Backus introduced the FP language which motivated a new kind of programming [BACK78]. Much of the current research in program transformation has centered around this new approach [BIRD84, BELL84]. Many researchers describe their transformations in terms of rewriting rules or transformation rules [HUET80]. These provide a uniform description of the intended transformation without considering implementation details.

The latter approach to program transformation motivated us to apply those methods and ideas to the translation of relational queries. The translation of aggregate functions is a nontrivial example to demonstrate several aspects of a rule-based translation. We also argue that the successive translation of the sort function and the aggregate function into a more efficient program has several advantages over a hand-coded program to implement the desired improvement.

First, independently defined functions for sorting and aggregation support the design of a modular, high-level interface for query evaluation. Deriving desirable improvements from the combination of sorting and aggregation relieves the optimizer from considering another operation during optimization, thus simplifying the optimizer's task.

Second, the use of rules allows a simple description of the performed transformation which may easily lead to an experimental implementation of a query translation system. Each rule performs a sound transformation which guarantees that the newly generated program correctly performs the computation initially specified.

Third, the transformation may be effective even if the aggregate function is not known to the system in advance. The suggested transformation could be applied to combine a user provided function with internally defined processing strategies to guarantee a more efficient query execution.

Our goal for the translation of functions sort_merge and sum_by is twofold. On the one hand we would like to use the FP notation to perform high level transformations. On the other hand we have to guarantee fast execution of user-submitted queries. To accomplish both goals, we introduce two kinds of transformation: Horizontal transformation and vertical transformation. During the first transformation we manipulate progranss, specified in an FP-like notation, to generate the program which performs aggregation while sorting. The high-level specification simplifies the manipulation of functions and control structures without considering details of their implementation. Vertical transformation then translates the high level program description into an iterative program to guarantee fast execution.

## 3. The Definition of Sort_Merge and Sum_By

This section defines the functions sort_merge and sum_by. For the horizontal transformation we describe the function sort merge in an FP-like notation using the three operators map, tree, and $L$. Operators map and tree specify two different control structures. They determine how to access sets of tuples during sorting. During the transformation we create new functions by combining existing ones. We therefore introduce operator $L$ to express the combination of functions. Throughnut this paper we use lists instead of relations to represent sets of tuples. We prefer lists over relations to avoid confusion and to guarantee notational uniformity.

Operator map is motivated by the corresponding Lisp operator which denotes a loop-like control structure without specifying its exact implementation. The meaning of the expression (map flist) with $f$ being a function of arity one is defined as "applying function $f$ to each clement in the list." For example, consider $f$ to be the square function sqr and list to be the list $\langle 1,5,3\rangle$, then (map sqr list) returns the three element list $\langle 1,25,9\rangle$ without specifying the order in which we apply function sqr to the initial list. Intuitively, operator map specifies to access the tuple list by applying function $f$ to each tuple individually.

In the above example we introduced a list of integers. However, we may also use lists containing other kinds of elements. For the definition of sort merge the elements of a list can be lists of elements. For example, if list consists of two lists $\langle 5,1,3\rangle$ and $<2,6,3\rangle$, and if sort denotes the sort function, then (map sort list) returns a list of sorted lists

$$
\langle\langle 1,3,5\rangle,\langle 2,3,6\rangle\rangle
$$

by applying function sort to each element, a list of integers, in the original list.

For the FP-like specification of the sort-merge algorithm, we need to introduce another control structure operator, called tree, which denotes a "divide and conquer" control structure [BACK78, WILL82]. (tree flist), with $f$ being a function of arity two divides a list recursively into a left and a right part until the list contains one element. On each level of the recursion $f$ is applied to the results returned form the previous level of recursion. For example, let + denote the addition function and let :list be $\langle 1,5,7,4\rangle$, then (tree + list) performs the computation as shown in Figure 1 returning the expected result of 17 .


Figure 1: Computation tree for (free $+\langle\mathbf{1}, 5,7,4\rangle$ )

Formally, tree is defined by
$($ (ree $f$ list $)=\left\{\begin{array}{l}\text { list }, \text { if the list has one element } \\ (f(\text { iree } f(\text { lf list }))(\text { tree } f(\text { rg list })))\end{array}\right.$
where If and $r g$ are functions which divide a list into a left and a right part of (almost) equal length, i.e.

$$
\begin{aligned}
& \left(I f<e_{1}, \ldots, e_{n}>\right)=\left\langle e_{1}, \ldots, e_{n / 2}\right\rangle \\
& \left.\left(r g<e_{1}, \ldots, e_{n}\right\rangle\right)=\left\langle e_{n / 2+1}, \ldots, e_{n}\right\rangle
\end{aligned}
$$

The third operator, $L$, is used for the combination of functions during the transformation. Informally, let $f_{1}$ and $f_{2}$ be two functions of arity $m$ and $n$, respectively, then $\left(L f_{1} f_{2}\right)$ denotes the combination $\left(f_{1}\left(f_{2} x_{1} \ldots x_{n}\right) y_{2} \ldots y_{m}\right)$ of both functions substituting $f_{2}$ for $f_{1}$ 's first parameter.

We use the operators map and tree to define the sort-merge algorithm which performs sorting as follows [KNUT73]. During the first phase a list of tuples is divided into runs, i.e. tuples lists of equal length. Each run is sorted before starting the merge-phase. This phase begins with pairs of sorted runs that are merged into one
sorted run. Each subsequent phase merges pairs of runs, produced in the previous phase, into a sorted new run which is twice as long as the input runs. Figure 2 shows an example of the merge phase.


Figure 2: Sort-Merge Computation Tree

The tree operator exactly resembles the computational behavior performed during the second phase. According to the explanation we define the merge-sort (merge__sort A list) by the expression $^{\text {m }}$

$$
\left(\text { tree merge }_{A}\left(\text { map sort }_{A}(\text { convert list })\right)\right)
$$

where function convert converts a list of elements into runs, i.e. a list of tuple lists. Those runs are subsequently sorted on values of attribute $A$ as specified by (map sort $A_{A}$ list) before the merge phase begins. Whenever merge is applied to two sorted lists, the result is a sorted list consisting of elements of both inputs. The "tree-like" application of merge ultimately returns one sorted run of elements.

For a complete definition of the merge-sort we need to specify functions sort, merge, and convert. As function convert is not important for the fater transformation we do not provide a detailed definition. We define function (sort $A_{A}$ list) by another tree expression (tree merge, list) which specifies to recursively split the tuple list into a left and a right part before merging them back again, based on the $A$ values of the individual tuples. With the definitions of merge_sort and sort it remains to define function merge $A_{A}$ which we could implement by a PASCAL-like program. However, for clarity and ease of manipulation we prefer a recursive definition in a Lisp-like notation which uses the following operations on lists ${ }^{\mathbf{2}}$ :
(first list)
returns the first element of the list.
(rest list)
returns a new list by removing the first element of the list.
*empty*
returns the empty list
(out ele list)
creates a new list whose first element ele is followed by all elements in list.

## (empty? list)

evaluates to true if the list is empty and to false if list is an expression of the form (out ele list).

To define program merge $A_{A}$ we propose a small functional language in a Lisp-like notation which is well suited for formal manipulation. We shall describe the target language informally. The language is

[^1]based on expressions. An expression is either a variable, a function expression, or a conditional expression. A function expression has the form $\left(f_{1} t_{1} \ldots t_{n}\right)$, where $f_{1}$ is a function symbol and $t_{i}, i=1, \ldots, n$ are expressions called actual parameters, A conditional expression has the form (if $t_{1} t_{2} t_{3}$ ), where $t_{1}, t_{2}, t_{3}$ are expressions. If $t_{1}$ evaluates to true, then the value of $t_{2}$ is the value of the expression, otherwise it is the value of $t_{3}$.

We define the function ( merge $_{A} l_{1} l_{2}$ ) which merges two lists $l_{1}, l_{2}$, sorted on attribute $A$, as follows. Let $g r_{A}$ ? and $e q_{A}$ ? be two functions comparing two elements $e_{1}, e_{2}$. If the $A$ value of $e_{1}$ is greater (equal) than the $A$ value of $e_{2}$, then the functions return true, otherwise they return false:

```
(if (empty? l1 ) l2
    (if (empty? l2) l
        (if (gr}\mp@subsup{A}{A}{}\mathrm{ ? (first l}\mp@subsup{l}{1}{})(\mathrm{ first }\mp@subsup{l}{2}{})
            (out (first l ) (merge }\mp@subsup{A}{1}{}\mp@subsup{l}{1}{(rest l}\mp@subsup{l}{2}{\prime}))
            (if (eq_}\mp@subsup{|}{1}{}\mathrm{ ? (first l l ) (firstl}\mp@subsup{l}{2}{\prime}
            (out (first l l ) (merge }\mp@subsup{A}{1}{\prime}\mp@subsup{l}{1}{(rest I L )))
            (out (first I ) (\mp@subsup{merge }{A}{(}(\mathrm{ rest I I ) I I))))))})
```

The program for ( $\operatorname{merge}_{A} l_{1} l_{2}$ ) first checks if one of the lists is empty. If so, either $l_{1}$ or $l_{2}$ is returned. If both lists have at least one element, those are compared on the values of $A$. If the $A$ value of the first element in $l_{2}$ is less than or equal to the $A$ value of the first element in $l_{1}$, we output the first element of $l_{2}$ and continue the merge recursively after having removed the first element from $l_{2}$. In case the $A$ value of the first element in $l_{1}$ is less, that element is returned followed by all elements resulting from the recursive call ( merge $_{A}\left(\right.$ rest $\left.l_{1}\right) \cdot l_{2}$ ).

Similarly, we define the aggregate function (sum_by $y_{B, A} l_{1}$ ) which computes the sum of the $B$ values for the set of tuples having the same $A$ values. To compute the result correctly, sum_ $b y_{B, A}$ expects an input list which is sorted on the $A$ values. Its definition uses the function $\left(a d d_{B} e_{1} e_{2}\right)$ which adds the $B$ values of $e_{1}$ and $e_{2}$, creating a new tuple $\left\langle b_{1}+b_{2}, a\right\rangle$ with $e_{i}=\left\langle b_{i}, a\right\rangle$. (sum__by $y_{B, A} l_{1}$ ) is defined by the expression

```
(if (empty? l l ) *emply*
    (sum}\mp@subsup{\mp@code{B,A}}{(first l}{l})(\mathrm{ rest l}\mp@subsup{l}{1}{}))
```

where $\left(\operatorname{sum}_{B, A}\right.$ ele $\left.\mathrm{t}_{1}\right)$ is defined by

```
(if (empty? l ) (out ele li)
    (if (eq_}\mp@subsup{A}{1}{}\mathrm{ ele (first I I ))
        (\mp@subsup{\mathrm{ sum}}{B,A}{A}}(\mp@subsup{\mathrm{ add }}{B}{}\mathrm{ ele (first l l l ) (rest l}\mp@subsup{l}{1}{})
        (out ele (sum}\mp@subsup{\mp@code{B,A}}{(\mathrm{ first l}\mp@subsup{l}{1}{})(rest l}{l}))))
```

If $I_{1}$ is not empty, sum_by $\boldsymbol{B}_{B, A}$ calls the two parameter function $\operatorname{sum}_{B, A}$. The first parameter serves as an "accumulator". for summing up the $B$ values for the same $A$ value. If a new $A$ value is encountered, the "accumulated" element is returned followed by all elements resulting from the recursive call to function $\operatorname{sum}_{B, A}$.

## 4. The Transformation of Sort_Merge and Sum_By

Based on the definitions of the previous section, this section describes the transformation of the QEP

```
(sum_byb,A}(\mp@subsup{m}{B}{\prime
```

into an executable program. The operations, specified by this QEP, are to first sort the list based on values of attribute $A$ before applying the aggregate function sum_ $b y_{B, A}$ which computes the same of $B$ values for each $A$ value in the list. We carry out the transformation in two phases. First, horizontal transformation performs structural manipulation using the tree notation for the mergesort function. We show how the transformation intertwines both functions yielding a program which computes the aggregate function while sorting. Although the tree notation is well suited for the transformational purposes, its recursive nature does not guarantee an efficient execution. For this reason the vertical transformation replaces the "tree recursion" by iteration. We present two transformations into iterative programs which differ in their computational behavior. The first program generated maintains a treestructured computation; the second one resembles a left linear computation tree. We shall argue that both translation schemes can guarantee an efficient execution depending on the function which is performed during iteration.

During horizontal transformation sum_by $y_{B, A}$ and merge $A_{A}$ are combined by operator $L$. To translate their combination into an iterative program during vertical transformation, we generate the new function sum _merge m,A $^{\text {s }}$ which performs merging and aggregation simultaneously. The recursive form of the new function immediately leads to an iterative program form.

### 4.1. Horizontal Transformation

The horizontal transformation of

$$
\left(\text { sum__b }_{y_{\Gamma_{A}}}\left(\text { merge__sort }_{A} \text { list }\right)\right)
$$

is based on the following theorem which provides a sufficient condition for distributing a function $f_{i}$ over the tree operator.

## Theorem 1:

Let $f_{1}$ and $f_{2}$ be two functions and let $l_{1}, l_{2}, l_{3}$ be lists. If

$$
\left(f_{1}\left(f_{2} l_{1} l_{2}\right)\right)=\left(f_{1}\left(f_{2}\left(f_{1} l_{1}\right)\left(f_{1} l_{2}\right)\right)\right)
$$

then

$$
\left(f_{1}\left(\operatorname{tree} f_{2} l_{3}\right)\right)=\left(\operatorname{tree}\left(L f_{1} f_{2}\right)\left(\operatorname{map} f_{1} l_{3}\right)\right)
$$

The inductive proof of the theorem can be found in [FREY85a]. Intuitively, the condition of the theorem requires $f_{1}$ and $f_{2}$ to be "almost" independent. Since the two functions do not commute with each other, $f_{2}$ follows each application of $f_{1}$ in a tree-like computation.

by the definition of merge sort $_{A}$, we need to show that functions sum__by $y_{B, A}$ and merge $A_{A}$ satisfy the condition of the above theorem. Notice, that the input to both, merge $A_{A}$ and sum_by $y_{B, A}$, are lists sorted on attribute $A$. Informally, if merge $A_{A}$ is applied first, the result is a sorted list with the same tuples as in the two input lists. Applying sum__by $y_{B, A}$ yields a sorted list containing one tuple for each value of $\bar{A}$ recording the sum of $A$ 's $B$ values.

On the other hand, if we first apply sum $b y_{B, A}$ to both sorted lists $l_{1}, l_{2}$, we obtain two sorted lists $l_{1}^{\prime}, l_{2}^{\prime}$, each containing one tuple for each $A$ value recording the sum of all $B$ values. Applying function merge $A_{A}$ to $l_{1}^{\prime}$ and $l^{\prime}{ }_{2}$ results in a sorted list containing at most two successive tuples for cach $A$ valuc. Applying the aggregate function again yields the same aggregated list as for the first case.

As sum_ $b y_{B, A}$ and merge $e_{A}$ satisfy the condition, we can apply the theorem to the above expression, thus yielding the expression

```
(tree (L sum_by B,A merge }\mp@subsup{A}{A}{\prime}
    (map sum__by B,A}(\mp@subsup{m}{map sort}{A}(\mathrm{ (convert list))))
```

The operations specified by the nested subexpression (map sum__by $y_{B, A \ldots \text { ) are to sort all runs before applying the aggregate }}$ function sum_by $y_{B, A}$. However, we can avoid scanning the list of runs twice by performing the aggregate operation immediately after sorting the run. We therefore fold the nested map expressions into one map expression combining the sort and the aggregate function by operator $L$ :

$$
\begin{aligned}
& \left(\text { tree }\left(L \text { sum_by } y_{B, A} \text { merge }_{A}\right)\right. \\
& \left.\quad\left(\text { map }\left(L \text { sum_by } \quad b, A \text { sort }_{A}\right)(\text { convert list })\right)\right)
\end{aligned}
$$

which represents the first result of horizontal transformation. The expression determines to first convert a list of tuples into runs before applying the sort and aggregation function to each individual run. Finally, all runs are merged and aggregated using a tree-like computation.

We continue the horizontal transformation on the combination of functions

$$
\left(L \text { sum_ } \quad b y_{B, A} \operatorname{sort}_{A}\right)
$$

By the definitions of $\operatorname{sor}_{A}$ and $L$ in Section 3, we rewrite the combination into the expression

$$
\left(\text { sum_by } y_{B, A}\left(\text { tree merge }_{A} l i s t\right)\right)
$$

which allows us to apply Theorem 1 again. The resulting expression is

As the application of sum_by $y_{B, A}$ to each tuple of the run is superfluous, the previous expression reduces to

$$
\left(\text { tree }\left(L \text { sum_by } y_{B, A} \text { merge }_{A}\right) \text { list }\right)
$$

which constitutes the second result of the horizontal transformation. As each merge is immediately followed by the aggregate function the final list of tuples consists of one tuple for each $A$ value recording the sum of its $B$ values,

We may now combine both expressions by substituting the latter for ( $L$ sum_ $b y_{B, A}$ sort $_{A}$ ) into the former yielding the final expression of horizontal transformation:

```
(tree (L sum_byy,A merge }\mp@subsup{\mp@code{A}}{\mathrm{ )}}{\mathrm{ )}
    (map (tree (sum__by (i,A merge )) (convert list)))
```


### 4.2. Vertical Transformation

Since we are concerned with an fast execution of the programs which we generated in the previous subsection, we suggest to transform these high-level program specifications into iterative programs. The final expressions resulting from horizontal transformation show that we have to develop transformations for the tree operator, the map operator and the combination of functions merge $A_{A}$ and sum_by $y_{B, A}$. Operator map simply translates into a loop. We develop a transformation for the more complex tree operator and the function combination in the next two subsections. Surprisingly, we can describe both transformations independently. Since the performed transformations are quite complex, we represent only the final iterative programs without going into the details of the transformation itself. The interested reader is referred to [FREY85a].

### 4.2.1. Transforming the Tree Operator into Iteration

At the beginning of this section we mentioned that the control structure operator tree has a natural recursive implementation. For fast execution we would like to replace the "tree recursion" by iteration. We derive two different iterative programs with different computational behavior [FREY85a]. The first iterative program maintains the tree structure by performing the desired computation in rounds, thus simulating the tree specification in a bottom up manner. Figure 3 shows the computational behavior of the first iterative program in case of $f$ being the merge function.


Figure 3: The Bottom-Up Computation in Rounds

During each round function $f$ is applied to runs of the same length before the next round is encountered. If $f$ is the merge function, then the iterative program exactly performs the computation as shown in Figure 2.

In contrast to the first iterative program the second one we generate performs a computation which resembles a left linear computation tree. We show the computation tree in Figure 4 for $f$ being the merge function.


Figure 4：The Left Linear Computation

During each iteration function $f$ is applied to one initial run and the＂intermediate＂result which has been accumulated so far．If $f$ is the merge function，then the iterative program successively merges each run with a tuple list whose length increases with every merge． Clearly，the transformation has changed the $n \log n$ complexity of the initial tree specification into a program which has a $n^{2}$ com－ plexity with $n$ being the initial number of tuples．

Despite the disadvantage in this example there may exist cases where one would favor the second transformation．To justify our claim we examine in more detail the representation of tuple lists by relations in database systems．Usually，relations are stored on secondary storage．The DBMS needs to access relations in memory to perform operations necessary for the query evaluation．For this purpose，the systems maintains a buffer which keeps part of the relations in memory．Its contents is changed frequently by reading from and writing to secondary storage whenever the DBMS has finished its operations on one part and needs buffer space for processing other parts．As read and write operations are time consuming，they often dominate the overall query evaluation time． Decreasing the number of read and write operations usually im－ proves the overall processing time．

Suppose that the buffer is large enough to store three initial runs． Let $f$ be the combination of functions sum＿$b y_{B, A}$ and merge $A_{A}$ ． Furthermore，assume that the new run resulting from merging and applying aggregation has（approximately）the same length as the initial two input runs．The output run then still fits into the available buffer space．If the condition holds for every application of $f$ ，the second transformation turns out to be superior as far as read and write operations are concerned．During the execution of the second iterative program the intermediate run always resides in memory and is immediately available as input for the next application of sum $b y_{B, A}$ and merge $A_{A}$ ．In contrast，the iterative program generated by the first transformation writes out each run created in round $i$ before reading it again in round $i+1$ ．More formally，if there are $n$ initial runs which need to be processed by sum＿by $y_{B, A}$ and merge $_{A}$ ，the first iterative program initiates $2 n-1$ read and $n-1$ write operations ${ }^{3}$ under the above assumptions．The program generated by the second transformation uses only $n$ read operations thus evaluating the aggregate much faster．

The assumptions made above are realistic for the computation of aggregates．Often，the number of values，which determine the partition of tuples into subsets，is much smaller than the number of tuples in the relation．Consider the example introduced in the introduction of this paper．Assume that the relation EMP contains 10,000 tuples describing employees in 50 different departments．If each initial run contains more than 50 tuples and if it fits into one buffer block，the above conditions are satisfied．The initial sort， followed by the aggregate function，results in at most 50 tuples recording the partial sum for each department existing in that run． If the subsequent phase performs merging and aggregation using the second iterative program the execution resembles a computation
with one＂bucket＂for each department always residing in memory．

## 4．2．2．Transforming Functions Sum＿by and Merge into Iteration

The final expressions resulting from horizontal transformation con－ tain the combination of functions

$$
\left(L \text { sum__by }, A, \operatorname{merge}_{A}\right)
$$

Using the definition of $L$ of Section 2，we can rewrite the expres－ sion into the more familiar form

```
(sum__byB,A}(\mp@subsup{\mathrm{ merge }}{A}{\prime}/\mp@subsup{l}{1}{\prime}\mp@subsup{l}{2}{})
```

Based on the recursive definitions of both functions，the iterative program would consist of two successive loops，one performing the sort，the other performing aggregation．To avoid the intermediate sorted list，we would like to generate a program which consists of one loop to perform sorting and aggregation at the same time． Based on recursive definition functions sum＿by $y_{B, A}$ and merge $e_{A}$ ，we show in［FREY85a］how to generate a new function sum＿merge ${ }_{B, A}$ from the initial function definitions．A nontrivial，laborious trans－ formation yields the new function sum merge ${ }_{B, A}$ which performs aggregation and sorting simultaneously．（sum＿merge $e_{B, A} l_{1} l_{2}$ ） which has the following recursive form：

```
(if (empty? l) l}\mp@subsup{l}{2}{
    (if (empty? l) l}\mp@subsup{l}{1}{
        (if (gr 
            (out (first l ) (sum_merge }\mp@subsup{A}{1}{\prime}(\mathrm{ rest }\mp@subsup{l}{2}{}))
            (if (eq_⿻肀二
                    (out(add B
                    (out (first l l) (sum_merge, (rest ( l ) l l ))))))
```

The sum＿merge $e_{B, A}$ program differs from the merge $e_{B}$ program only in case the $A$ values of the first elements in both lists are the same． The newly generated program performs the aggregation by function $\operatorname{add}_{B}$ instead of returning one tuple．Using the transformation schemes in［BURS77］or［COHE80］，the recursive form of the new program immediately leads to the following iterative program：

```
result := *empty*;
WHILE not (empty? }\mp@subsup{l}{1}{}\mathrm{ ) and not (empty? l}\mp@subsup{l}{2}{}\mathrm{ ) DO
    IF (gr 
        result := (out (first }\mp@subsup{l}{2}{}\mathrm{ ) result); l}\mp@subsup{l}{2}{}:=(\mathrm{ (rest }\mp@subsup{l}{2}{}\mathrm{ );
        ELSE
            IF (eq}\mp@subsup{A}{A}{}\mathrm{ ? (first l}\mp@subsup{l}{1}{})\mathrm{ (first l}\mp@subsup{l}{2}{\prime})\mathrm{ ) THEN
            result := (out (add A (first l}\mp@subsup{l}{1}{})(\mathrm{ first }\mp@subsup{l}{2}{})) result);
            l}:=(\mathrm{ rest }\mp@subsup{l}{1}{\prime});\mp@subsup{l}{2}{}:=(\mathrm{ rest }\mp@subsup{l}{2}{})
        ELSE
            result := (out (first ll) result); l}\mp@subsup{l}{1}{}:=(\mathrm{ (rest }\mp@subsup{l}{1}{})
END_DO;
IF (empty? l l) THEN
    result := (out l2 result)
ELSE
    result := (out ll result);
```

Comparing both forms for function merge_ $b y_{B, A}$, the reader may

[^2]convince him(her)self that the recursive form is much more suited for formal manipulation than the iterative version.

## 5. Generalization of Transformation

In the previous section we demonstrated horizontal and vertical transformation using the aggregate function sum_by $y_{B, A}$. In the following subsection we extend the transformation to other aggregate functions by introducing two new control structure operators. These are used to redefine all aggregate functions. The second subsection then summarizes all transformations by defining four transformation rules. We apply them to a final example.

### 5.1. Redefinition of Aggregate Functions

The major question is what needs to be changed for the transformation of other aggregate functions. Clearly, the horizontal transformation rests on the condition of Theorem 1. Do we have to repeat vertical transformation for every aggregate function separately? The analysis of other aggregate functions, such as "the minimum (maximum) $B$ value for each value of attribute $A^{\prime \prime}$ or "number of tuples having the same $A$ value", reveals that only the functional parr of the aggregation changes, that is the function applied while scanning the list of tuples. The control structure, that dictates how to scan the list of elements, always remains the same. This observation leads to the definition of a new control structure operator, $a g g_{\ldots} b \dot{y}_{A}$, which clearly separates the two aspects. Informally, (agg_by $f_{1} l_{1}$ ) with $f_{1}$ being a function of arity two and $l_{1}$ being a list implements a computation which "accumulates the final result by applying function $f_{1}$ to subsequent elements in the list $l_{1}$ as long as they have the same $A$ values". More formally; we define function ( $a g g_{2} b y_{A} f_{1} I_{1}$ ) to be

```
(if (empty? \1) *empty*
    (aggA fl (first I ) (rest li)))
```

where $\left(a g g_{A} f_{1}\right.$ ele $\left.l_{1}\right)$ is defined by

```
(if (empty? l}\mp@subsup{l}{1}{})(\mathrm{ out ele l l)
    (if (eq\mp@subsup{|}{A}{}? ele (first I_))
        (aggA fll
        (out ele (agg}\mp@subsup{A}{1}{}\mp@subsup{f}{1}{(first}\mp@subsup{l}{1}{})(\mathrm{ rest ( }\mp@subsup{l}{1}{\prime})))
```

The only difference between functions $a g g_{\ldots} b y_{B, A}$ and sum_ $b y_{B, A}$ is that the former has an additional parameter specifying the function $f_{1}$ which is applied during the scan of $l_{1}$.

Similarly, we generalize (sum_merge ${ }_{B, A} l_{1} l_{2}$ ) by introducing function
$\left(\operatorname{agg} \_\right.$merge $\left._{A} f_{1} l_{1} l_{2}\right)$
which applies function $f_{1}$ to any two elements with the same $A$ values while merging. This generalization again distinguishes between the control structure, used to scan the list of tuples, and the function performed during the scan. We define (agg_merge $f_{1} f_{1} l_{2}$ ) by

```
(if (empty? l1) )}\mp@subsup{l}{2}{
    (if (empty? l2) l
        (if (gr 
        (out (first l ) (agg__merge A fl l}\mp@subsup{l}{1}{(rest l}\mp@subsup{l}{2}{}))
        (if (eq_
            (out (fl (first l l ) (first l l ))
                        (agg_merge A}\mp@subsup{f}{1}{}\mp@subsup{l}{1}{\prime}(\mathrm{ rest l}\mp@subsup{l}{2}{\prime}))
            (out (first l l ) (agg__merge A}\mp@subsup{f}{1}{}(\mathrm{ rest lil l l ) )))))
```

In [FREY85a] we show that the combination of functions (agg_by $f_{1}\left(\right.$ merge $\left._{A} l_{1} l_{2}\right)$ ) translates into function (agg_merge $A_{A} f_{1} l_{1} l_{2}$ ) by exactly the same transformation as for the specialized case (sum_by $y_{B, A}\left(\right.$ merge $\left._{A} l_{1} l_{2}\right)$ ).

Using these more general control structure operators, we redefine (sum_by $y_{B, A} l i s t$ ) by

$$
\left(a g g_{\_} b y_{A} a d d_{B} \text { list }\right)
$$

where $a d d_{B}$ is the addition function specialized to add the $B$ values of two elements in the list. The new definition of $s u m \ldots b y_{B, A}$ nicely shows the distinct use of attributes $A$ and $B$. Values of attribute $A$ distinguish the different subsets on which to perform the aggregation. Attribute $B$ determines which values to aggregate on.

We may define other aggregate functions in a similar way. For instance, consider the functions ( $\max \quad b y_{B, A}$ list) and ( $\min \quad b y_{B, A}$ list), which compute the maximum and minimum $B$ value for each $A$ value in the list, respectively. We redefine both functions by (agg_by $\max _{B}$ list) and (agg_by $\min _{B}$ list) with functions $\max _{B}$ and $\min _{B}$ returning the tuple with the larger and smaller $B$ value, respectively.

The aggregate function (counf $f_{A}$ list), which counts the number of elements for each $A$ value in the list is implemented by
(agg by add CNT list)
where CNT is a new attribute whose initial value is 1 . Similarly, duplicate elimination is defined by

$$
\left(\text { agg _n by }_{A} \text { one list }\right)
$$

with $A$ being the list of all key attributes and with function (one $t_{1} t_{2}$ ) returning either tuple.

The aggregate function (average_by $y_{B, A}$ list), which computes the average $B$ value for each $A$ value, needs some more attention. As the average computation is based on counting and summation, we need to compute the number of tuples for each $A$ value and the sum of $B$ values for each $A$ value by (sum_by $y_{B A}$ list) and (count__by ${ }_{C N T, A}$ list) before dividing the sum by the count value.
If we rewrite both functions by their aggregate definitions (agg_by $a d d_{B}$ list) and (agg_by $a d d_{C N T}$ list) we recognize that both functions access the same list using the same control structure. Instead of accessing the list twice, we may apply both aggregate functions in "parallel" during one scan, thus leading to the expression

$$
\left(a g g_{\ldots} \quad b y_{A}\left\{a d d_{B} \quad a d d_{C N T}\right\} \text { list }\right)
$$

The \{ \} notation is used to denote the simultaneous application of a list of functions while scanning the list. Goldberg et al. call the proposed transformation horizontal loop fusion [GOLD84].

### 5.2. Transformation by Rules

To describe the translation of aggregate functions more formally, we introduce four transformation rules which summarize the transformation results of the previous subsections. A transformation rule has the form ( $t_{1} \rightarrow t_{2}$ ) which specifies to replace an occurrence of expression $t_{1}$ by expression $t_{2}$. For our transformation we define the following rules with $f_{1}, f_{2}$ being functions:

Rule I: Combination Rule

$$
\begin{gathered}
\left(\left\{\left(a g g \_b y_{A} f_{1} \text { list }\right)\left(a g g_{1} b y_{A} f_{2} l i s t\right)\right\}\right. \\
\left.\left(a g g_{\_} b y_{A}\left\{f_{1} f_{2}\right\} \text { list }\right)\right)
\end{gathered}
$$

Rule II: Tree Rule

$$
\left(\left(f_{1}\left(\text { tree } f_{2} \text { list }\right)\right) \rightarrow\left(\text { tree }\left(L f_{1} f_{2}\right)\left(\text { map } f_{1} \text { list }\right)\right)\right)
$$

Rule III: Fusion Rule
$\left(\left(\operatorname{map} f_{1}\left(\operatorname{map} f_{2} l i s t\right)\right) \rightarrow\left(\operatorname{map}\left(L f_{1} f_{2}\right) l i s t\right)\right)$
Rule IV: Aggregate-Merge Rule

$$
\left(\left(L\left(a g g_{\ldots} \quad b y_{A} f_{1}\right) \text { merge }_{A}\right) \rightarrow\left(a g g \quad \operatorname{merge}_{A} f_{1}\right)\right)
$$

The first rule allows to combine several aggregate functions which scan the same list using the same control structure. Rule II reflects the result of Theorem 1 . We can only apply the rule if the condition of the theorem is satisfied. Rule IIl combines two loops into one by applying both functions simultaneously, thus avoiding the creation of an intermediate list. The last rule replaces the functional combination of agg_by $y_{A}$ and merge $A_{A}$ by the newly derived function agg_merge ${ }_{A}$.

We demonstrate the transformation by rules using the SQL query

## SELECT AVG(Salary) FROM EMP <br> GROUP BY Department

which computes the average salary for each department in the EMP relation.

Before we can apply the rules in the given order, we translate the query into the internal form

$$
\text { (average__by Sal.,Dep. }\left(\text { merge__sort }_{\text {Dep. }} E M P\right) \text { ) }
$$

In the next step we decompose the the average aggregation into the aggregate functions sum_by Sal.,Dep. and count Dep. followed by function DIV Sal.,CNT which divides the sum and the count for each department value. Using the above definitions for both aggregate functions and the sort merge function we obtain the expression

```
(DIV \(_{\text {Sal.,CNT }}\)
    \(\left\{\left(a g g_{\text {__ }} y_{\text {Dep. }}{ }^{a d d_{\text {Sal }}}\right.\right.\).
        (tree merge \({ }_{\text {Dep. }}\) (map sort \({ }_{\text {Dep. }}\) (convert EMP))))
    (agg__by Dep. add \(_{C N T}\).
        (tree merge \({ }_{\text {Dep. }}\) (map sort \({ }_{\text {Dep. }}(\) convert \(\left.\left.E M P)\right)\right)\) ) \})
```

Applying Rule I once yields the expression

$$
\begin{aligned}
& \text { ( })^{\prime I} V_{\text {Sal..CNT }} \\
& \text { (agg_by Dep. }\left\{a d d_{S a l .} a d d_{C N T}\right\} \\
& \text { ( (ree merge }{ }_{\text {Dep. }} \text { (map sort }{ }_{\text {Dep. }} \text { (convert EMP))))) }
\end{aligned}
$$

Using Rule II and Rule III for the next transformation steps, we generate

$$
\begin{aligned}
& \text { (DIV }{ }_{\text {Sal.,CNT }} \\
& \text { (iree ( } L A G G \_B Y_{\text {Sal.,CNT, Dep. }} \text { merge }_{\text {Dep }} \text { ) } \\
& \text { ( } \left.\left.\operatorname{map}\left(L A \overline{G G} \quad B Y_{\text {Sal.,CNT,Dep. }} \text { sort }{ }_{\text {Dep. }}\right)(\text { convert } E M P)\right)\right) \text { ) } \\
& \text { with } A G G \_B Y_{\text {Sal., } C N T, D e p \text {. }} \text { being equal to } \\
& \text { (agg_by } \left.{ }_{\text {Dep }}\left\{a d d_{S a l .} a d d_{C N T}\right\}\right) \\
& \text { We apply Rule IV to derive } \\
& \text { (DIV }{ }_{\text {Sal., CNT }} \\
& \text { (tree (agg__merge }{ }_{\text {Dep }}\left\{\text { add }_{\text {Sal, }} \text { add }_{C N T}\right\} \text { ) } \\
& \text { (map (LAGG_B } Y_{\text {Sal.,CNT,Dep. }} \text { sorl }_{\text {Dep. }} \text { ) (convert EMP)))) }
\end{aligned}
$$

which represents the final result of the rule-based transformation. The expression defines the following order of operations: first, convert the list of tuples into runs, then apply sorting and aggregation to each of them. A tree-like computation produces one list of tuples each of which contains the number of tuples and the salary sum for each department. Using the definitions of $A G G_{\quad B} Y_{S a l,, C N T, D e p .}$ and the sort ${ }_{\text {Dep. }}$, we may complete the translation by the same transformation as shown in Subsection 4.1.

To guarantee fast execution we could continue the transformation of the tree expression into an iterative program based on the definitions for operators map and tree as described in Subsection 4.2.

## 6. Conclusion

We presented a improvement for the computation of aggregate functions which we derive by successive transformation by rules. We showed that independently defined programs for the aggregate and the sort functions can be translated systematically into a more efficient program which performs aggregation while sorting [KLUG82]. We generalize the translation to other aggregate functions as well by introducing a uniform notation which allows us to specify rules for their transformation.

In subsection 4.2.1. we compared the computational behavior of the two programs generated. To demonstrate the advantage of transformation, one would like to compare all three programs, i.e. the initial program which performs aggregation after sorting and the two derived programs, on experimental results. We did not perform such experiments to compare their performances. However, the results of Bitton et al. who use the idea of eliminating duplicates while sorting immediately applies to the computation of aggregates in rounds [BITT83].

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[^0]:    1 This research was done while the author was a student at Harvard University, Cambridge, MA 02138. The work was supported by the Office of Naval Rescarch under grant ONR-NO0014-83-K 0770.

[^1]:    2 These functions resemble the well known Lisp functions car, cdr, (), cons, and null?, respectively.

[^2]:    3 One may reduce the number of read and write operations slightly for the computation in rounds．However，the computation in rounds will never perform as well as the second iterative program．

